- How to integrate/steer a Robotic arm like Kinova or Assistive Technologies?

Robotic arms are interfaced via the seating actuator module of the powered wheelchair. The robotic arms can be controlled via CoMoveIT Smart in the same way as the seating actuators of the powered wheelchair (tilt, lift, recline, etc.).

The robotic arm control mode is located in the User Menu of the Omni2 screen in the **Seating Mode.**

Caution: In robotic arms, such as Kinova Jaco, a buddy button must be connected on the interface of the arm to allow the selection of the axis movement of the arm.